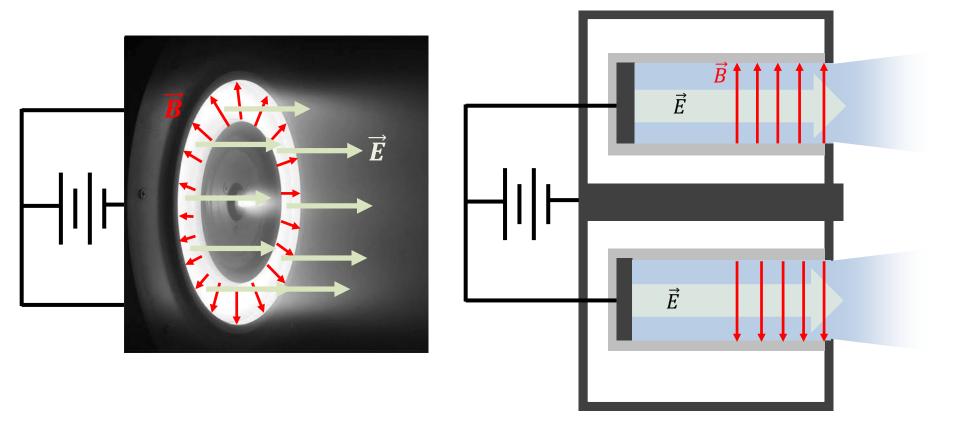


Data-driven Closure for Fluid Models of Hall Thrusters

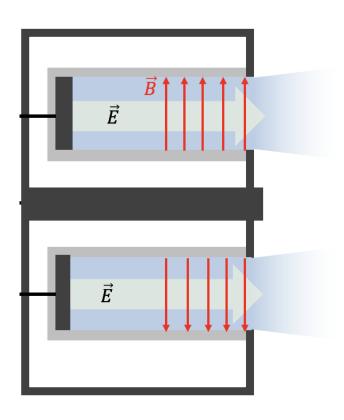
Benjamin Jorns
University of Michigan
Princeton University ExB Workshop



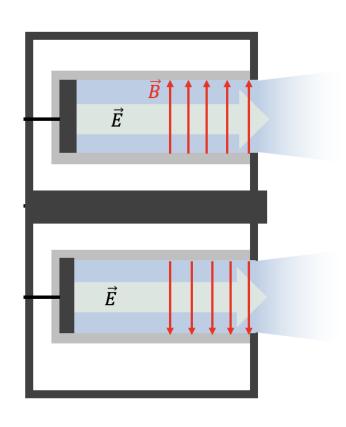
The Hall effect thruster for space propulsion











Closed set of classical equations that can be evaluated with standard techniques

Ion continuity

$$\frac{\partial n_i}{\partial t} + \nabla \cdot (n_i \boldsymbol{u}_i) = 0$$

Ion momentum

$$\frac{\partial (m_i n_i \boldsymbol{u}_i)}{\partial t} + \nabla \cdot (m_i n_i \boldsymbol{u}_i \boldsymbol{u}_i) = q \ n_i \boldsymbol{E} - \nu_i m_i (\boldsymbol{u}_i - \boldsymbol{u}_e)$$

Ohm's Law

$$v_e m_e n_e \boldsymbol{u_e} = -q n_e \vec{E} - \nabla P_e - q n_e \boldsymbol{u_e} \times \vec{B}$$

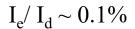
Electron Energy

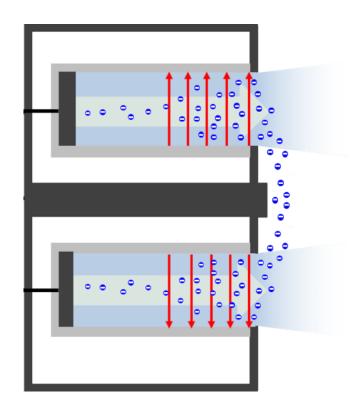
$$\frac{3}{2}n_e\frac{\partial T_e}{\partial t} = -qn_e\mathbf{E}\cdot\mathbf{u}_e - \nabla\cdot\left(\frac{5}{2}n_eT_e\mathbf{u}_e\right) + \frac{3}{2}T_e\nabla\cdot(n_e\mathbf{u}_e)$$

Current conservation

$$0 = \nabla \cdot (q n_e [\boldsymbol{u}_e - \boldsymbol{u}_i])$$







Electron cross-field current from evaluating classical equations

Ion continuity

$$\frac{\partial n_i}{\partial t} + \nabla \cdot (n_i \boldsymbol{u}_i) = 0$$

Ion momentum

$$\frac{\partial (m_i n_i \boldsymbol{u}_i)}{\partial t} + \nabla \cdot (m_i n_i \boldsymbol{u}_i \boldsymbol{u}_i) = q \ n_i \boldsymbol{E} - \nu_i m_i (\boldsymbol{u}_i - \boldsymbol{u}_e)$$

Ohm's Law

$$v_e m_e n_e \boldsymbol{u_e} = -q n_e \vec{E} - \nabla P_e - q n_e \boldsymbol{u_e} \times \vec{B}$$

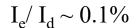
Electron Energy

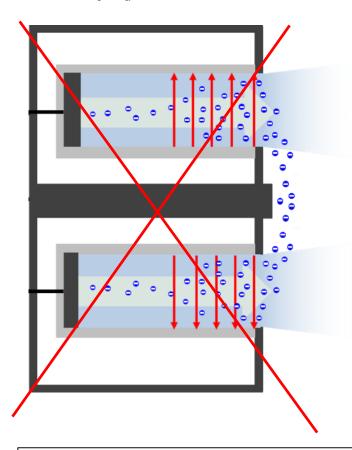
$$\frac{3}{2}n_e\frac{\partial T_e}{\partial t} = -qn_e\mathbf{E}\cdot\mathbf{u}_e - \nabla\cdot\left(\frac{5}{2}n_eT_e\mathbf{u}_e\right) + \frac{3}{2}T_e\nabla\cdot(n_e\mathbf{u}_e)$$

Current conservation

$$0 = \nabla \cdot (q n_e [\boldsymbol{u}_e - \boldsymbol{u}_i])$$







Actual cross-field current from evaluating equations <u>1000 x higher!</u>

Ion continuity

$$\frac{\partial n_i}{\partial t} + \nabla \cdot (n_i \boldsymbol{u}_i) = 0$$

Ion momentum

$$\frac{\partial (m_i n_i \boldsymbol{u}_i)}{\partial t} + \nabla \cdot (m_i n_i \boldsymbol{u}_i \boldsymbol{u}_i) = q \ n_i \boldsymbol{E} - \nu_i m_i (\boldsymbol{u}_i - \boldsymbol{u}_e)$$

Ohm's Law

$$v_e m_e n_e \boldsymbol{u_e} = -q n_e \vec{E} - \nabla P_e - q n_e \boldsymbol{u_e} \times \vec{B}$$

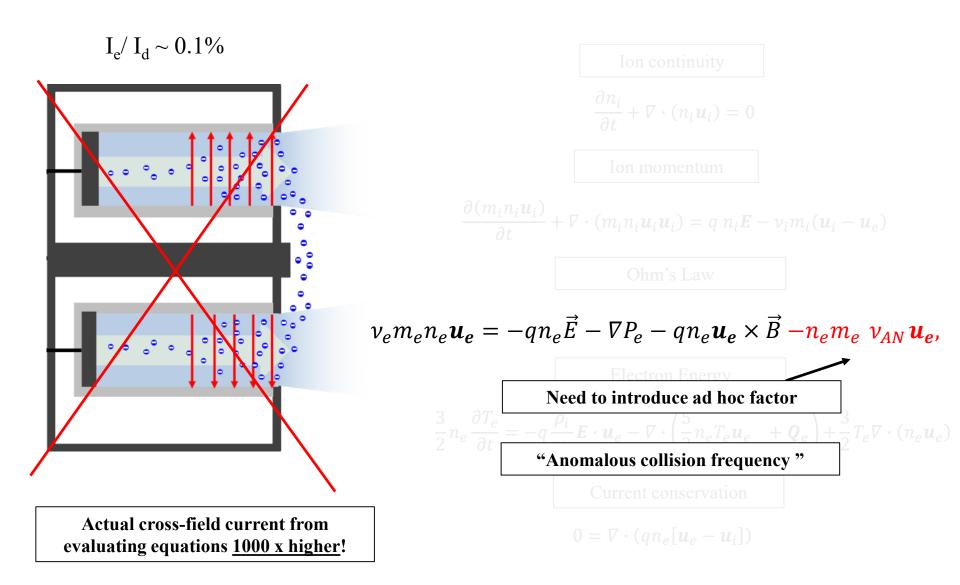
Electron Energy

$$\frac{3}{2}n_e\frac{\partial T_e}{\partial t} = -qn_e\mathbf{E}\cdot\mathbf{u}_e - \nabla\cdot\left(\frac{5}{2}n_eT_e\mathbf{u}_e\right) + \frac{3}{2}T_e\nabla\cdot(n_e\mathbf{u}_e)$$

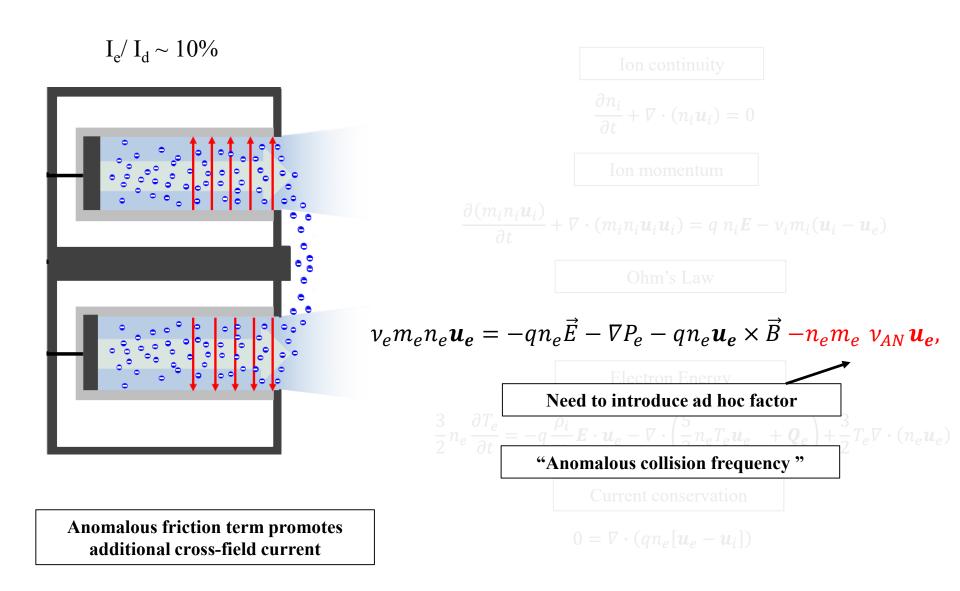
Current conservation

$$0 = \nabla \cdot (q n_e [\boldsymbol{u}_e - \boldsymbol{u}_i])$$

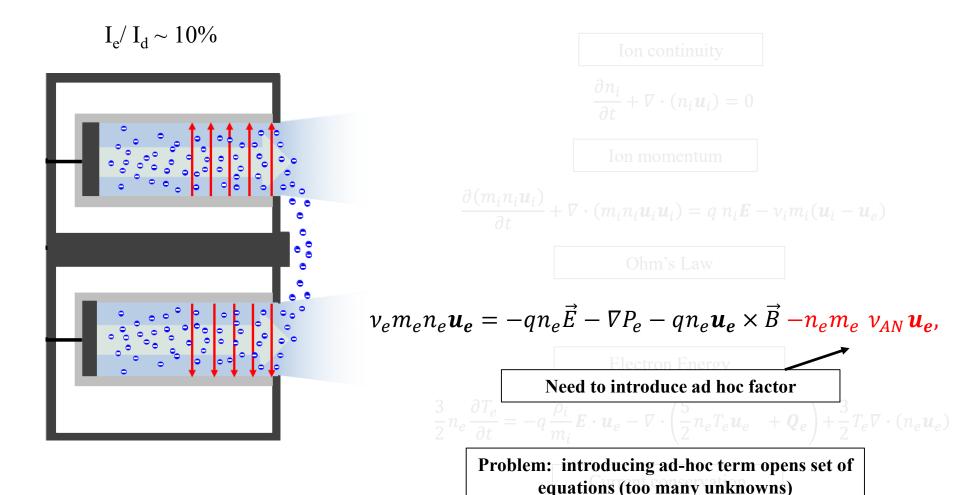






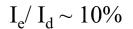


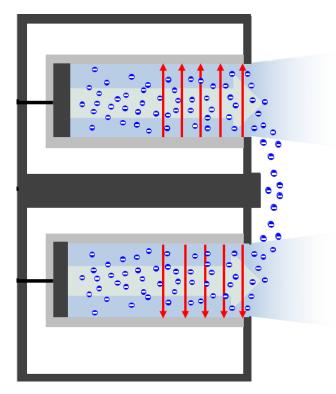




Anomalous friction term promotes additional cross-field current







We need a functional form for $v_{AN}(T_e, n_e,...)$ that depends on classical fluid parameters

Ion momentum

$$\frac{\partial (m_i n_i \mathbf{u}_i)}{\partial t} + \nabla \cdot (m_i n_i \mathbf{u}_i \mathbf{u}_i) = q \ n_i \mathbf{E} - \nu_i m_i (\mathbf{u}_i - \mathbf{u}_e)$$

Ohm's Law

$$v_e m_e n_e \boldsymbol{u_e} = -q n_e \vec{E} - \nabla P_e - q n_e \boldsymbol{u_e} \times \vec{B} - n_e m_e \ v_{AN} \boldsymbol{u_e},$$

Need to introduce ad hoc factor

$$\frac{3}{2}n_e\frac{\partial T_e}{\partial t} = -q\frac{\rho_i}{m_i}\mathbf{E}\cdot\mathbf{u}_e - \nabla\cdot\left(\frac{5}{2}n_eT_e\mathbf{u}_e + \mathbf{Q}_e\right) + \frac{3}{2}T_e\nabla\cdot(n_e\mathbf{u}_e)$$

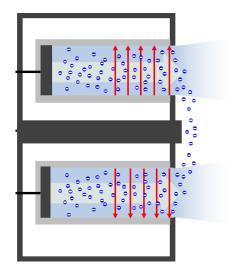
Problem: introducing ad-hoc term opens set of equations (too many unknowns)

$$0 = \nabla \cdot (q n_e [\mathbf{u}_e - \mathbf{u}_i])$$

Anomalous friction term promotes additional cross-field current



$$\vec{F}_{AN} = -n_e m_e \, \nu_{AN} \boldsymbol{u}_e$$



^{*}N. Gascon, M. Dudeck, and S. Barral, PoP, vol. 10, no. 10, 2003

[†] J. M. Fife and M. Martinez-Sanchez/ IEPC-95-24

[‡] M. A. Cappelli, C. V. Young, E. Cha, and E. Fernandez, PoP, vol. 22, no. 11, 2015.

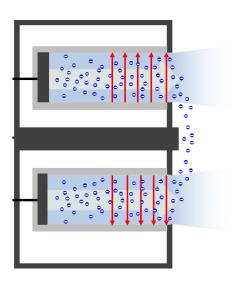
T. Lafleur, S. D. Baalrud, and P. Chabert, PoP, vol. 23, no. 5, 2016.



$$\vec{F}_{AN} = -n_e m_e \, \nu_{AN} \boldsymbol{u}_e$$

Wall Interactions*

$$\nu_{AN} = \beta \sqrt{T_e}$$



Bohm Diffusion†

$$\nu_{AN} = \frac{1}{K} \, \omega_{ce}$$

Instabilities[‡]

$$v_{AN} = \frac{1}{K} \omega_{ce} \left(\frac{\mathbf{v}_{de}}{c_s} \right)^2$$

$$v_{AN} = \frac{|\nabla \cdot (\vec{u}_i n_e T_e)|}{m_e c_s n_e \mathbf{v}_{de}}$$

^{*}N. Gascon, M. Dudeck, and S. Barral, *PoP*, vol. 10, no. 10, 2003

[†] J. M. Fife and M. Martinez-Sanchez/ IEPC-95-24

[‡] M. A. Cappelli, C. V. Young, E. Cha, and E. Fernandez, PoP, vol. 22, no. 11, 2015.

T. Lafleur, S. D. Baalrud, and P. Chabert, PoP, vol. 23, no. 5, 2016.



$$ec{F}_{AN} = -n_e m_e \, v_{AN} oldsymbol{u}_e$$

Closure models from first-principles are potentially predictive

$$v_{AN} = \beta \sqrt{T_e}$$

Models have to date have had limitations, yielding qualitative agreement over only limited range of conditions

Bohm Diffusion

Possible that reality is too complicated or models or too reduced fidelity

$$v_{AN} = \frac{1}{K} \omega_{ce}$$

^{*}N. Gascon, M. Dudeck, and S. Barral, *PoP*, vol. 10, no. 10, 2003

[†] J. M. Fife and M. Martinez-Sanchez/ IEPC-95-24

M. A. Cappelli, C. V. Young, E. Cha, and E. Fernandez, *PoP*, vol. 22, no. 11, 2015.



$$\vec{F}_{AN} = -n_e m_e \, \nu_{AN} \boldsymbol{u}_e$$

Closure models from first-principles are potentially predictive

 $\nu_{AN} = \beta \sqrt{T_e}$

Models have to date have had limitations, yielding qualitative agreement over only limited range of conditions

Bohm Diffusion

Possible that reality is too complicated or models or too reduced fidelity

Alternative: empirical form for collision frequency

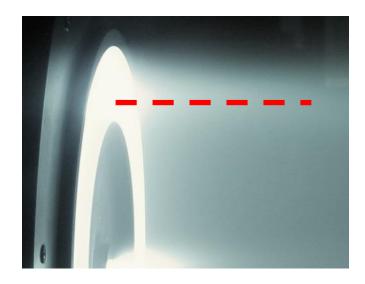
^{*}N. Gascon, M. Dudeck, and S. Barral, *PoP*, vol. 10, no. 10, 2003

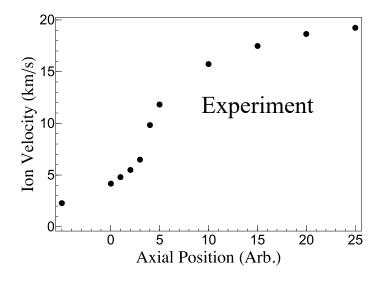
[†] J. M. Fife and M. Martinez-Sanchez/ IEPC-95-24

M. A. Cappelli, C. V. Young, E. Cha, and E. Fernandez, *PoP*, vol. 22, no. 11, 2015.

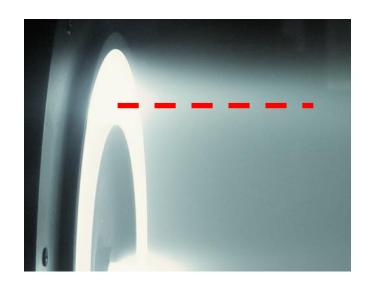
T. Lafleur, S. D. Baalrud, and P. Chabert, PoP, vol. 23, no. 5, 2016.

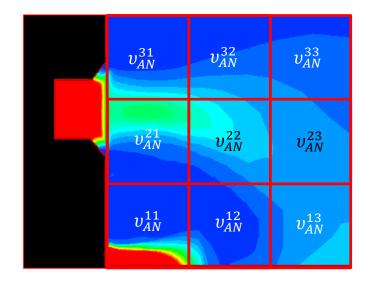


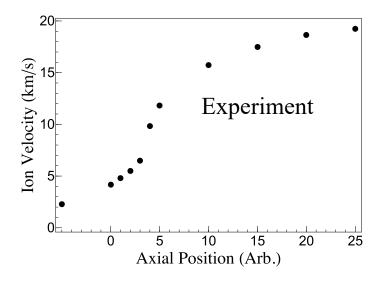


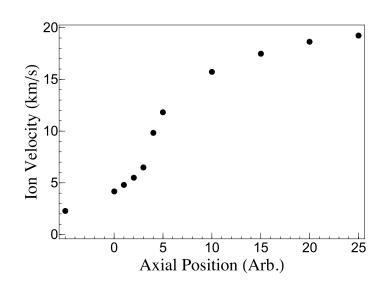




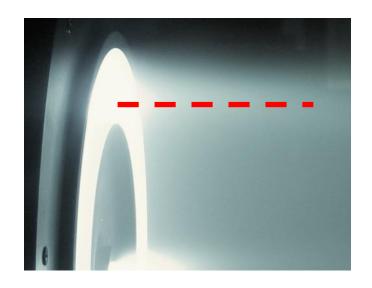


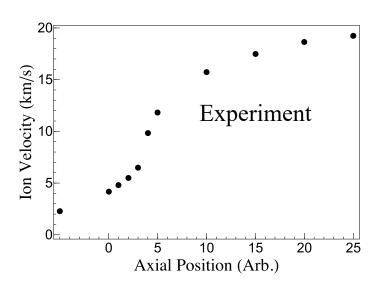


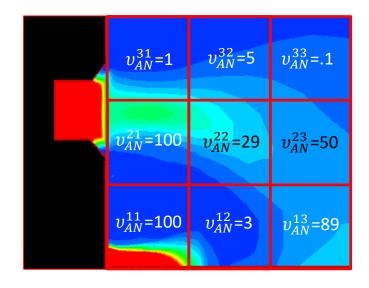


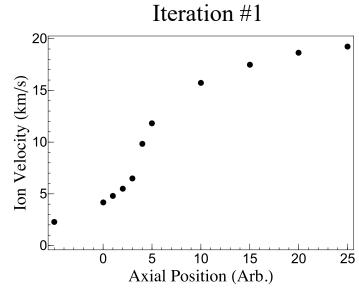




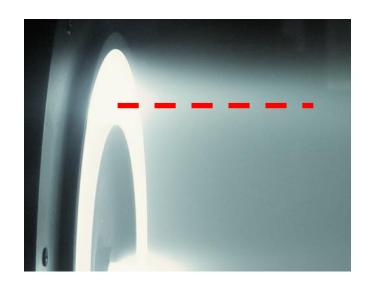


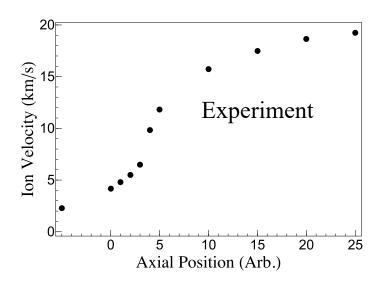


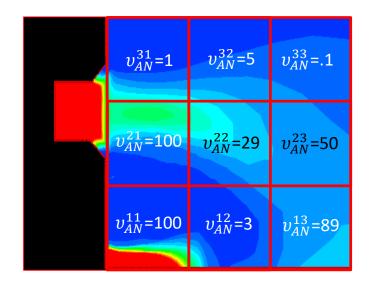


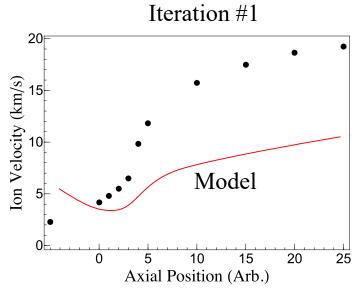




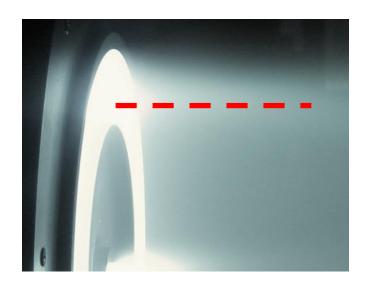


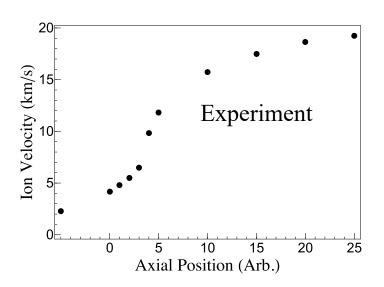


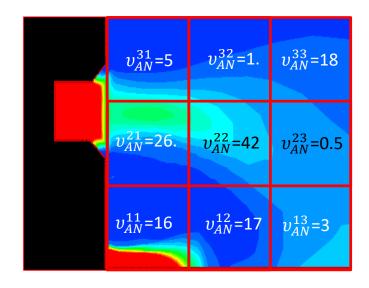


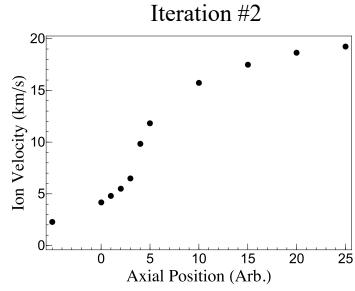




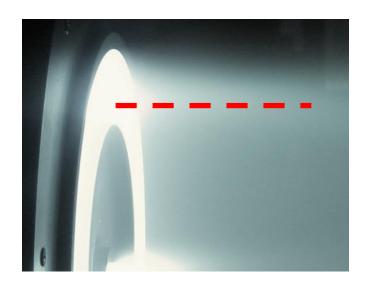


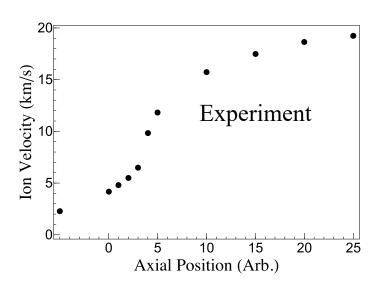


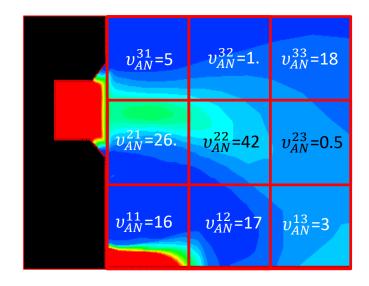


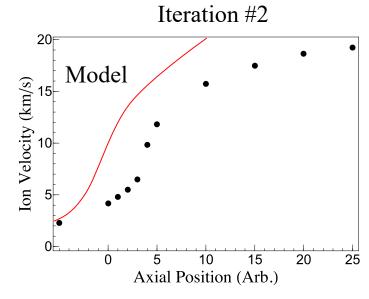




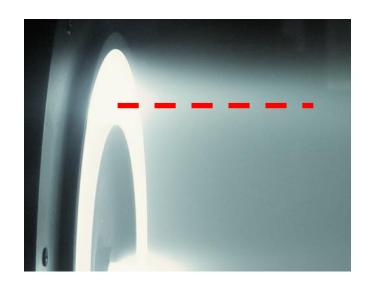


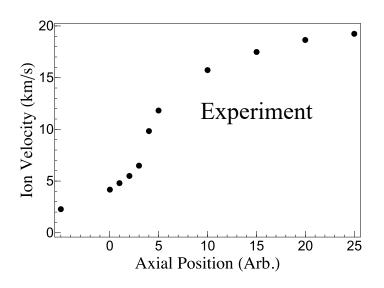


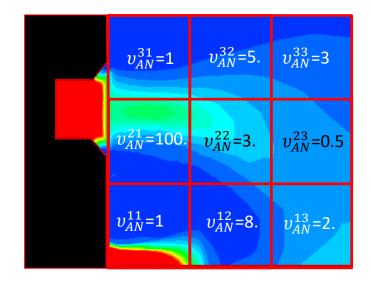


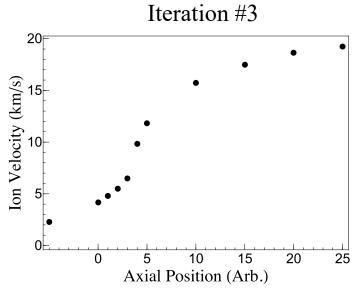




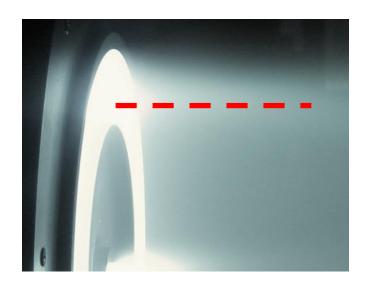


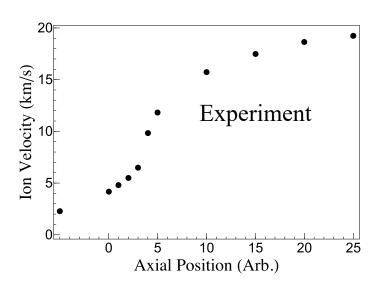


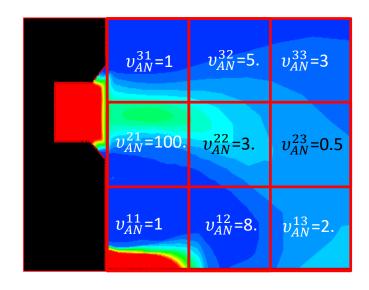


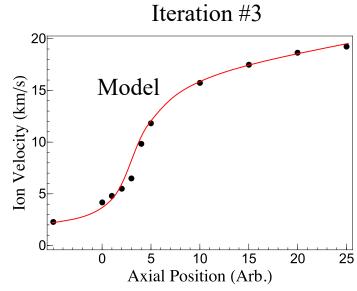






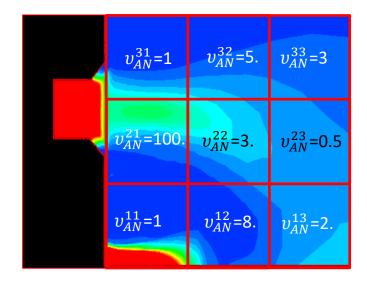


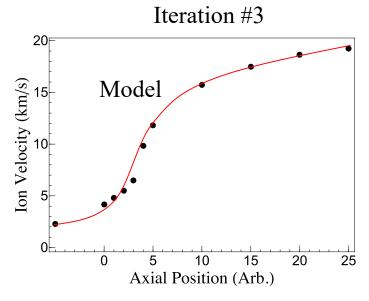






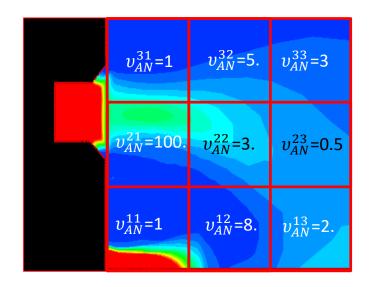
- Yields excellent agreement with experimental results for a given operating condition
- Collision frequency is specified empirically. Only applicable for data set used for validation

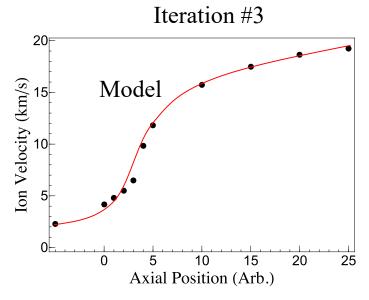






- Yields excellent agreement with experimental results for a given operating condition
- Collision frequency is specified empirically. Only applicable for data set used for validation
- To date, empirical models have not been predictive

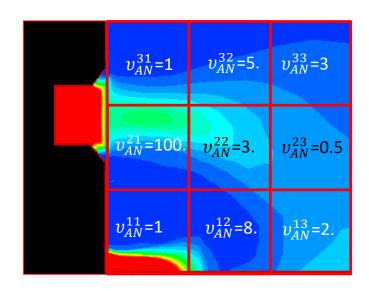


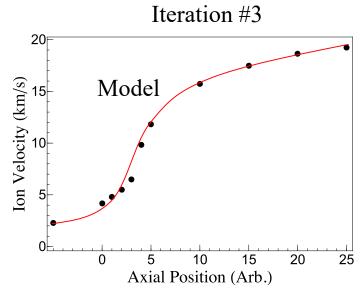




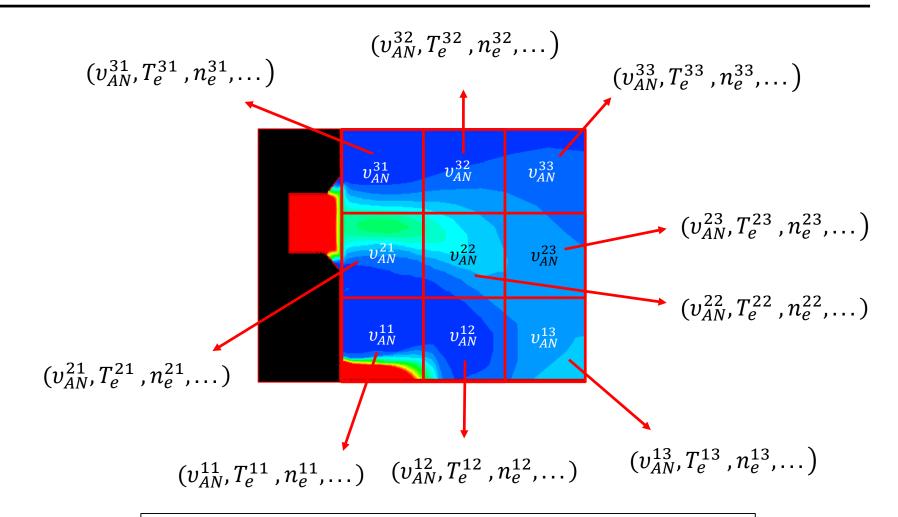
- Yields excellent agreement with experimental results for a given operating condition
- Collision frequency is specified empirically. Only applicable for data set used for validation
- To date, empirical models have not been predictive

Hypothesis: we can use empirical data to generate a functional form, $v_{AN}(T_e, n_e, ...)$



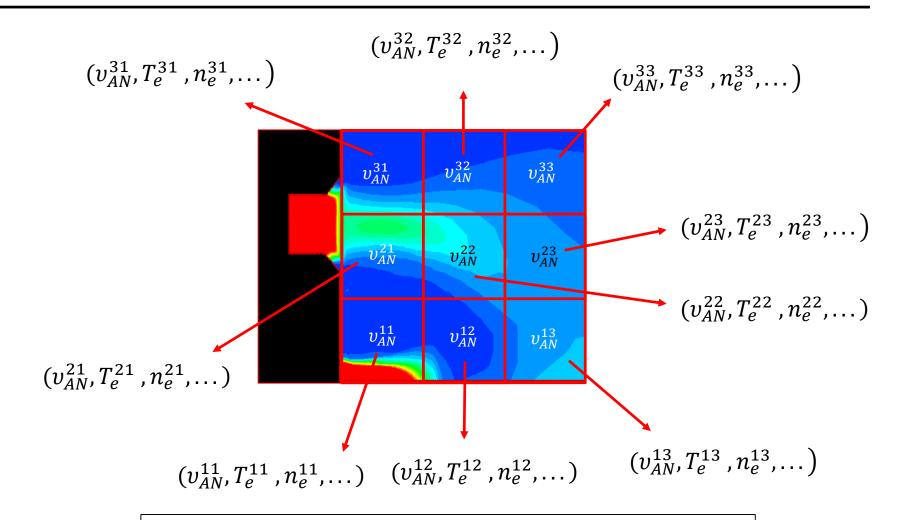






Each point from empirical model yields data point

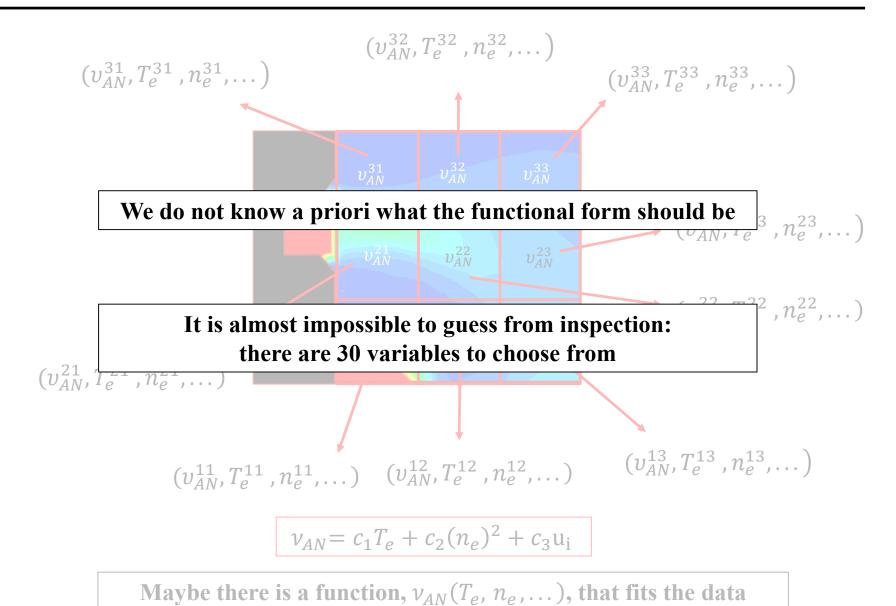




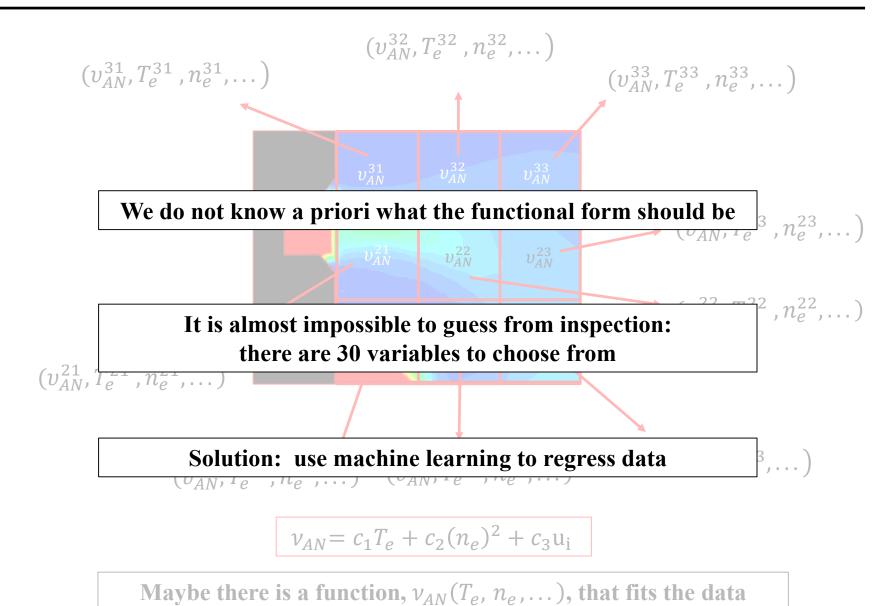
Each point from empirical model yields data point

Maybe there is a function, $v_{AN}(T_e, n_e, ...)$, that fits the data





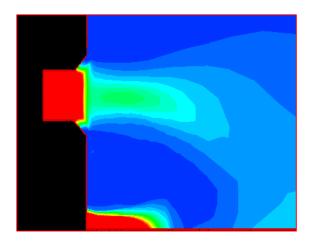








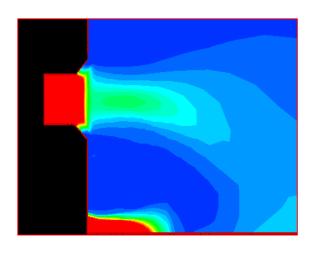
Generate datasets from empirically validated codes



7 operating conditions from 4 different thrusters from Hall2De*: 700 data points



Generate datasets from empirically validated codes



7 operating conditions from 4 different thrusters from Hall2De*: 700 data points

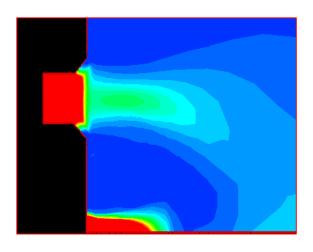
Prepare datasets for regression

Frequencies normalized by electron cyclotron frequency, ω_{ce}	
lon plasma frequency	ω_{pi}
Classical electron collision frequency	f _e
Classical ion collision frequency	f_i
Velocities normalized by ion sound speed, c_s	
lon axial velocity	u_i
Electron Hall velocity	v _{de}
Length scales normalized by electron Larmor radius, \mathbf{r}_{ce}	
Debye length	λ_{de}
Pressure gradient length-scale	$L_P = P_e/\nabla P_e$
lon drift velocity length-scale	$L_{ui} = u_i / \nabla u_i$

8 normalized lengthscales, velocities, and frequencies



Generate datasets from empirically validated codes



7 operating conditions from 4 different thrusters from Hall2De*: 700 data points

Prepare datasets for regression

Frequencies normalized by electron cyclotron frequency, ω_{ce}	
ω_{pi}	
f_e	
f_i	
Velocities normalized by ion sound speed, $ c_s $	
u_i	
v_{de}	
Length scales normalized by electron Larmor radius, \mathbf{r}_{ce}	
λ_{de}	
$L_P = P_e/\nabla P_e$	
$L_{ui}=u_i/\nabla u_i$	

8 normalized lengthscales, velocities, and frequencies

Apply ML regression algorithm

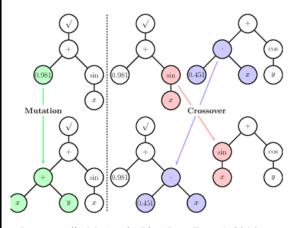
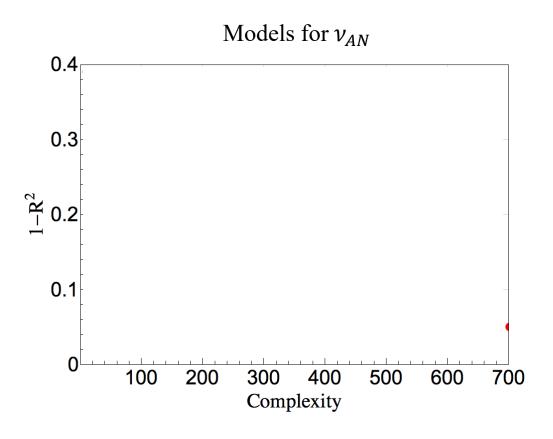


Image credit: M. Quade, Phys Rev. E. no 1. 2016

DataModeler symbolic regression from *Evolved Analytics*

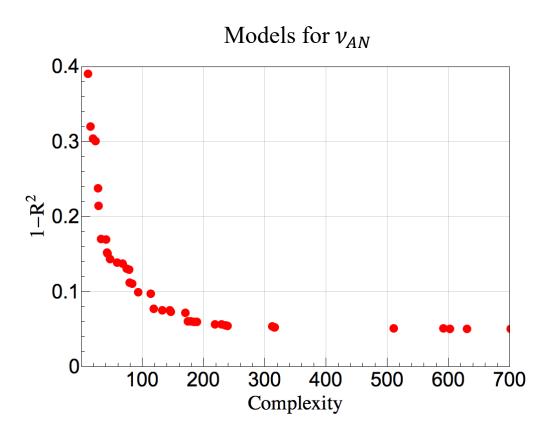


Symbolic regression Pareto front



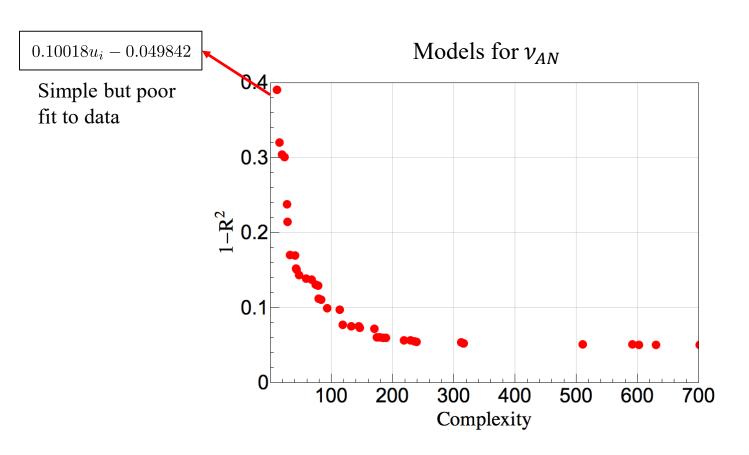


Symbolic regression Pareto front



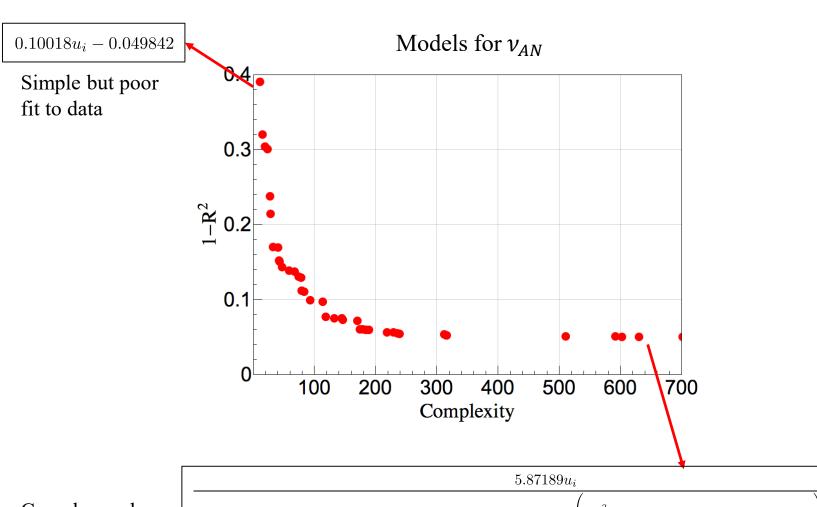


Symbolic regression Pareto front





Symbolic regression Pareto front

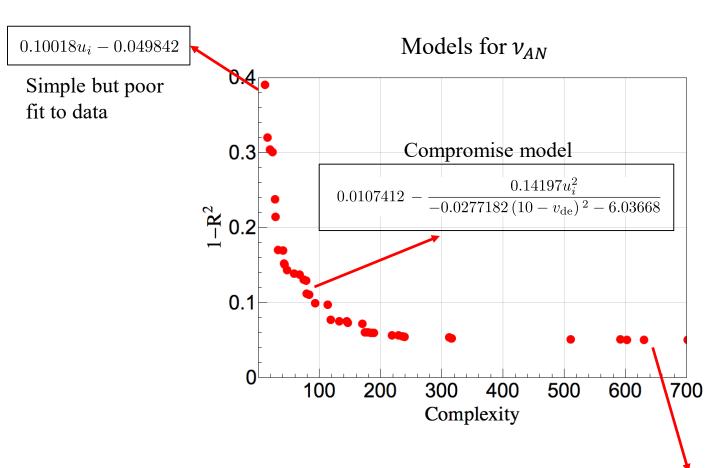


Complex and overfits data

$$\frac{5.87189u_{i}}{\frac{(v_{\text{de}}-10)^{4}}{u_{i}^{4}} + \left(-u_{i} - \frac{\lambda_{\text{de}}}{\sqrt{f_{e}}} + 10\right)^{2} - (u_{i}-8)^{2} + 4u_{i} - v_{\text{de}} + \frac{\left(\frac{v_{\text{de}}^{2}}{16} - u_{i} + \lambda_{\text{de}} + \frac{4}{u_{i}\left(-u_{i} - \frac{\lambda_{\text{de}}}{\sqrt{f_{e}}} + 10\right)} + 2.79118\right)^{2}}{u_{i}^{2}} + 23.6732}$$



Symbolic regression Pareto front

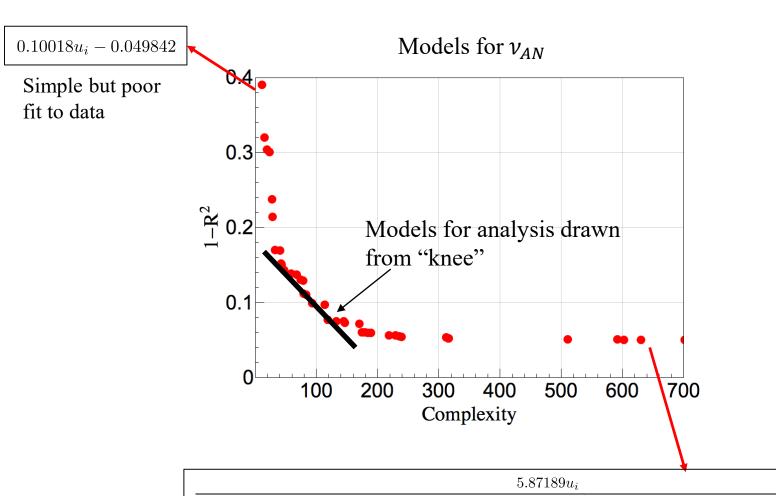


Complex and overfits data

$$\frac{5.87189u_{i}}{\frac{(v_{\text{de}}-10)^{4}}{u_{i}^{4}} + \left(-u_{i} - \frac{\lambda_{\text{de}}}{\sqrt{f_{e}}} + 10\right)^{2} - (u_{i}-8)^{2} + 4u_{i} - v_{\text{de}} + \frac{\left(\frac{v_{\text{de}}^{2}}{16} - u_{i} + \lambda_{\text{de}} + \frac{4}{u_{i}\left(-u_{i} - \frac{\lambda_{\text{de}}}{\sqrt{f_{e}}} + 10\right)} + 2.79118\right)^{2}}{u_{i}^{2}} + 23.6732}$$



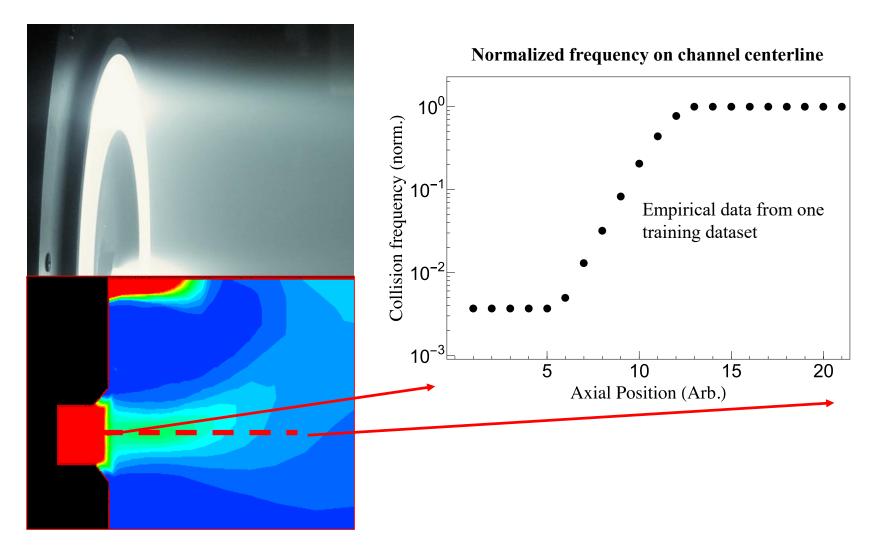
Symbolic regression Pareto front



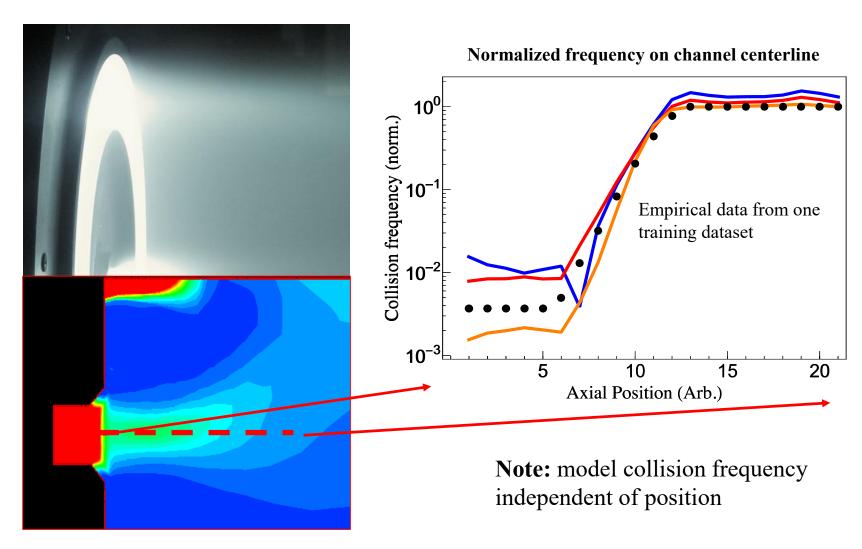
Complex and overfits data

$$\frac{5.87189u_{i}}{\frac{(v_{\text{de}}-10)^{4}}{u_{i}^{4}} + \left(-u_{i} - \frac{\lambda_{\text{de}}}{\sqrt{f_{e}}} + 10\right)^{2} - (u_{i}-8)^{2} + 4u_{i} - v_{\text{de}} + \frac{\left(\frac{v_{\text{de}}^{2}}{16} - u_{i} + \lambda_{\text{de}} + \frac{4}{u_{i}\left(-u_{i} - \frac{\lambda_{\text{de}}}{\sqrt{f_{e}}} + 10\right)} + 2.79118\right)^{2}}{u_{i}^{2}} + 23.6732}$$

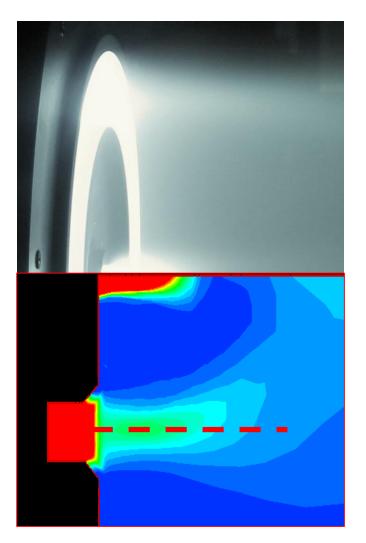




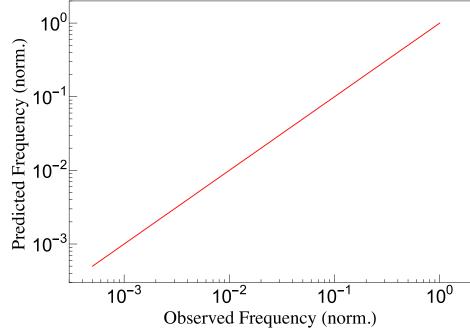




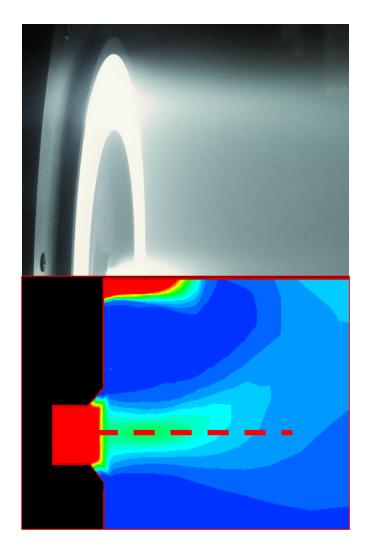




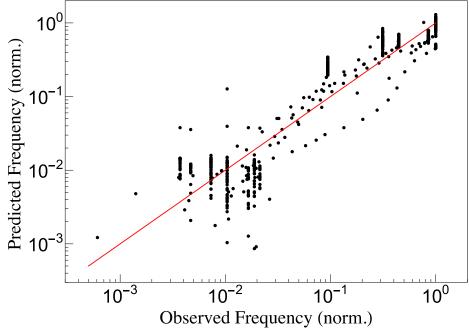
Response plot of model from Pareto front





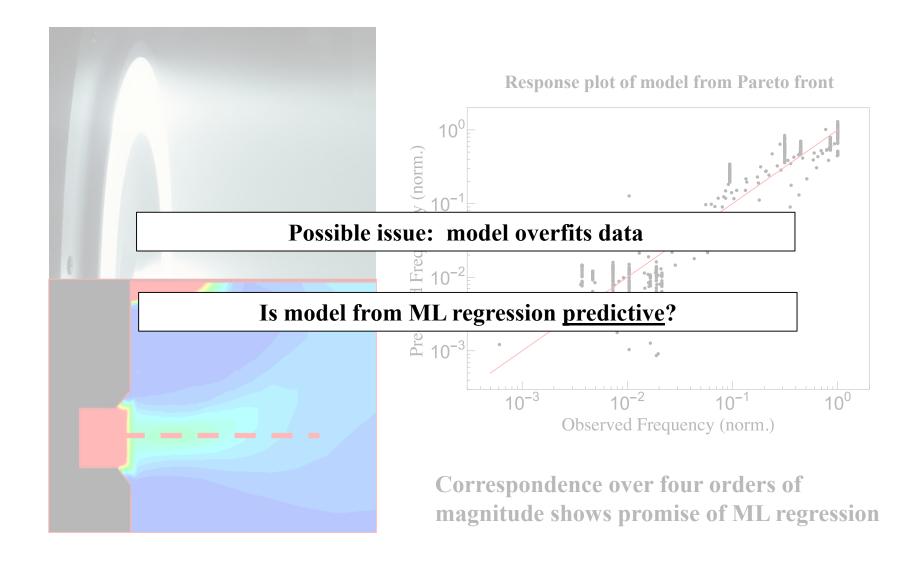


Response plot of model from Pareto front



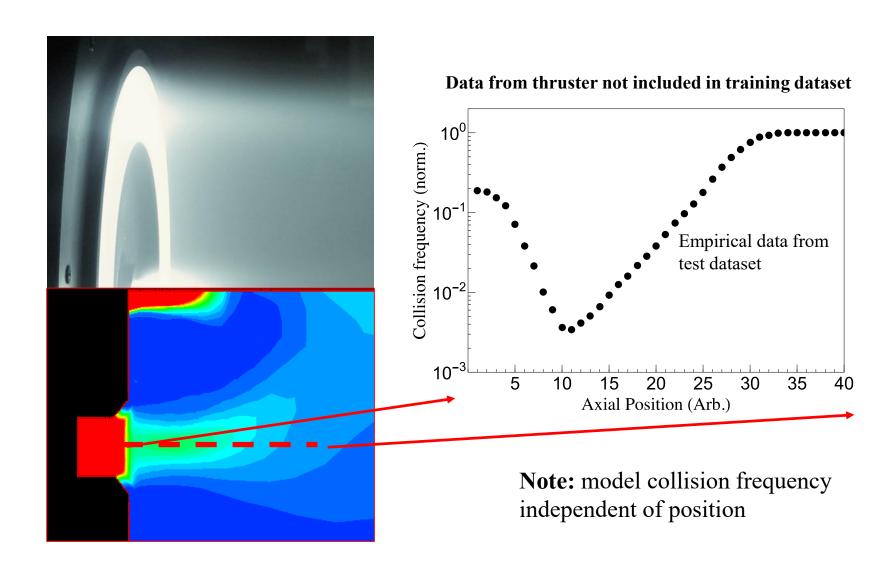
Correspondence over four orders of magnitude shows promise of ML regression





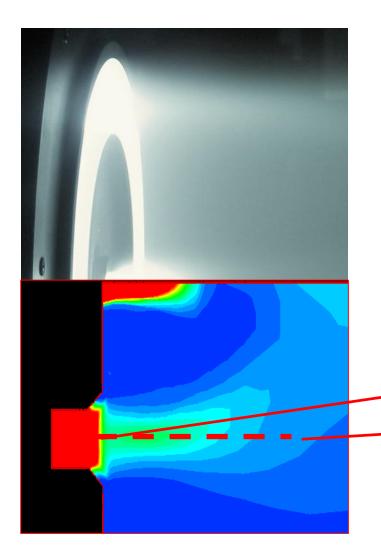


Predictive capability of model

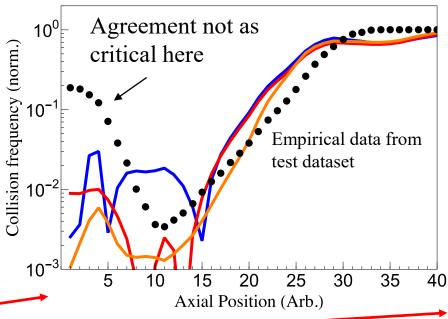




Predictive capability of model



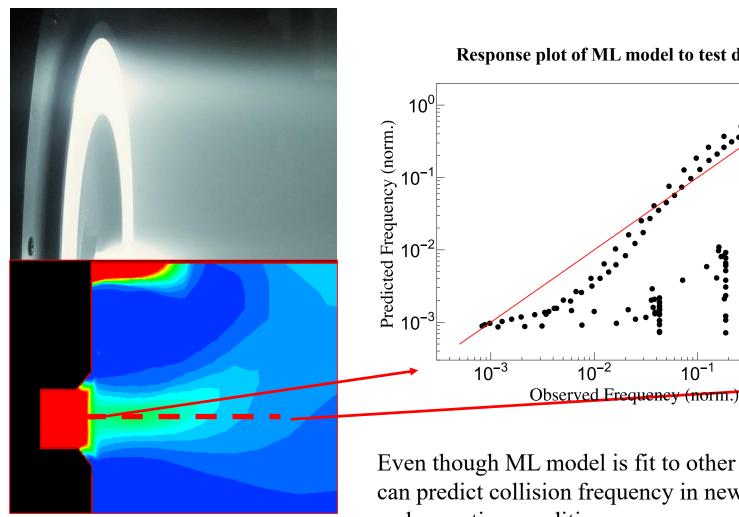
Data from thruster not included in training dataset



Note: model collision frequency independent of position



Predictive capability of model



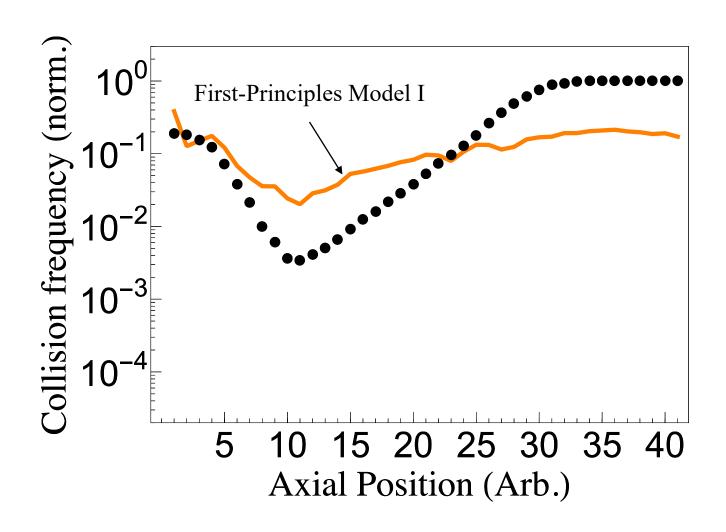
Response plot of ML model to test data

Even though ML model is fit to other data, it can predict collision frequency in new thruster and operating condition

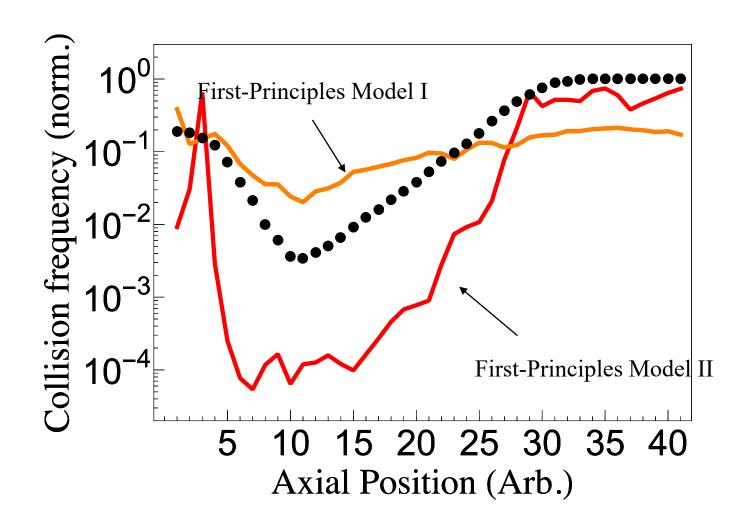
 $10^{\overline{0}}$

10⁻¹

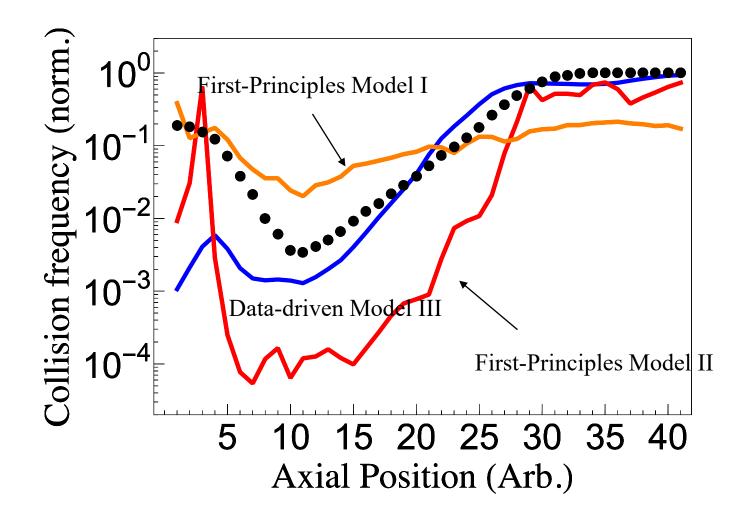






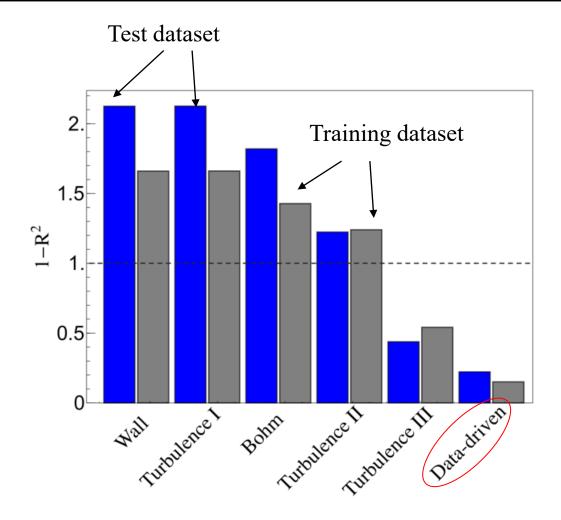






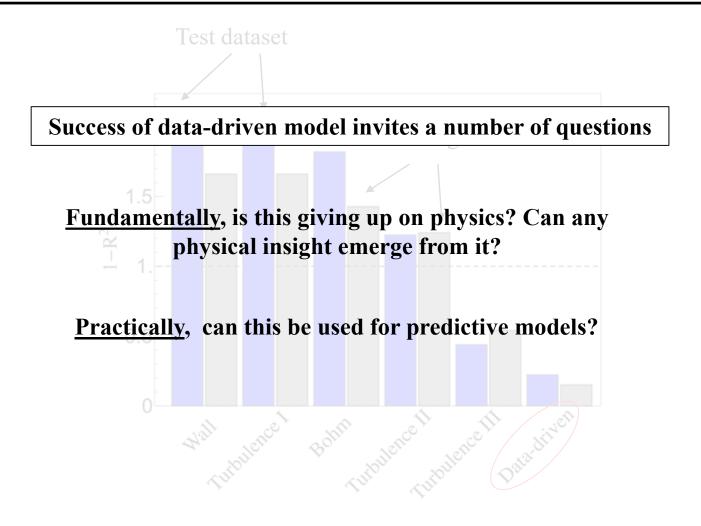
ML model has best correspondence and predictive capability of proposed closures



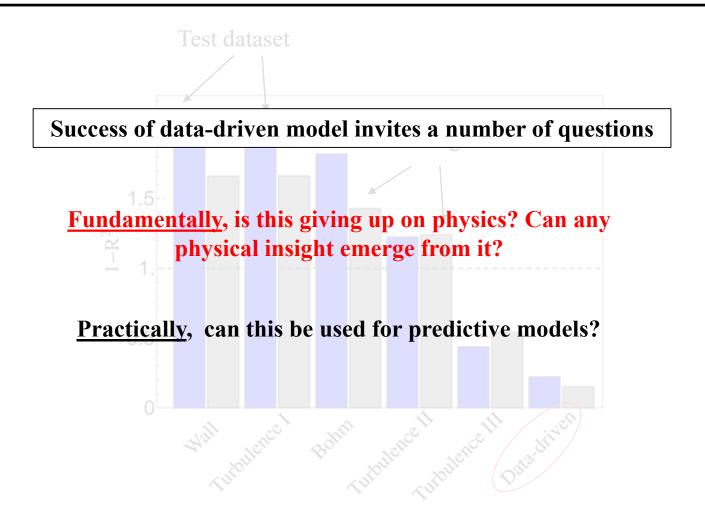


ML model has best correspondence and predictive capability of proposed closures



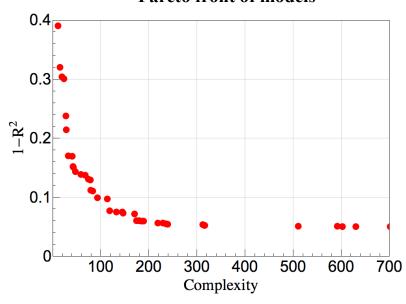








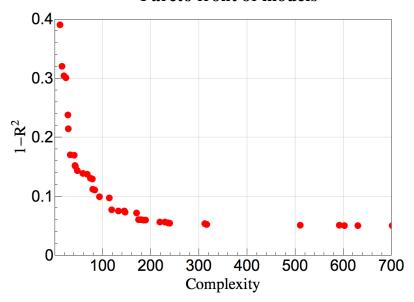




From these models, are there are any variables that are more common than others?

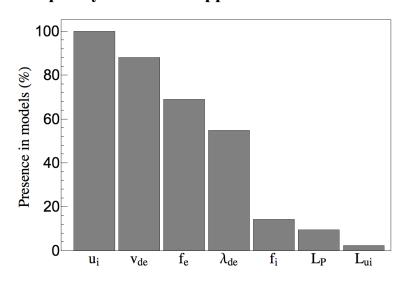






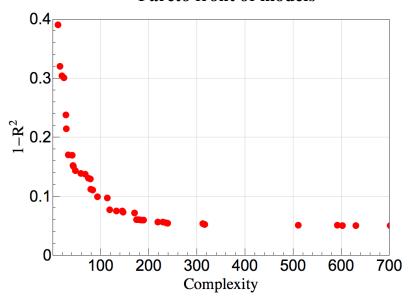
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Frequency of variable appearance in best models



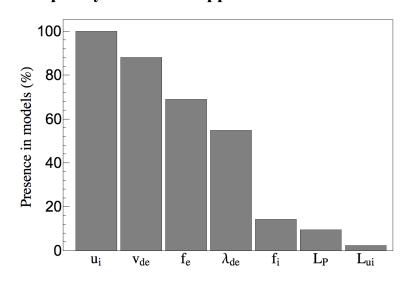






From these models, are there are any variables that are more common than others?

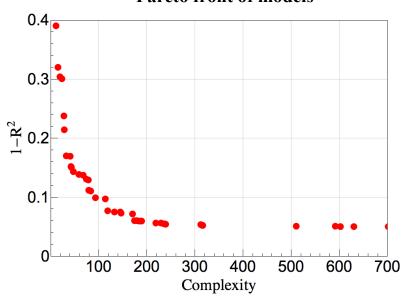
Frequency of variable appearance in best models



Ion drift and Hall drift dominant variables

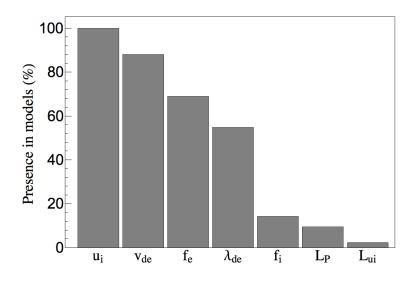


Pareto front of models



From these models, are there are any variables that are more common than others?

Frequency of variable appearance in best models

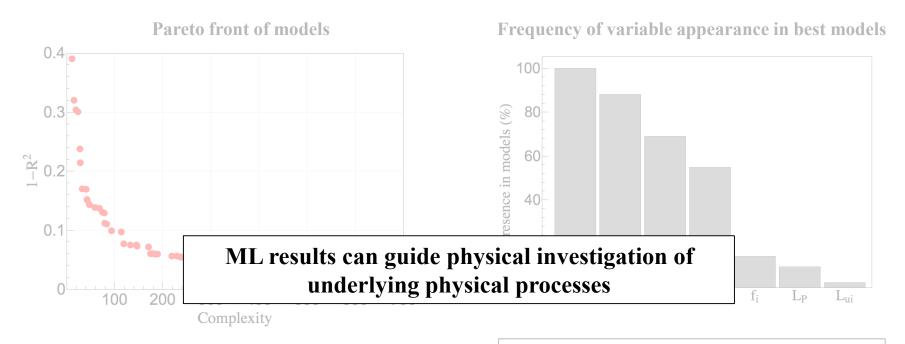


Ion drift and Hall drift dominant variables

Search for a first-principles mechanism that depends on these parameters

Electron cyclotron drift instability one example





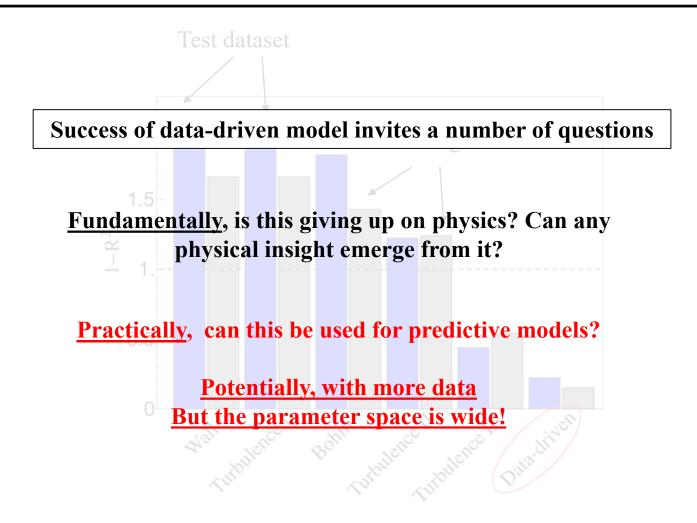
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Ion drift and Hall drift dominant variables

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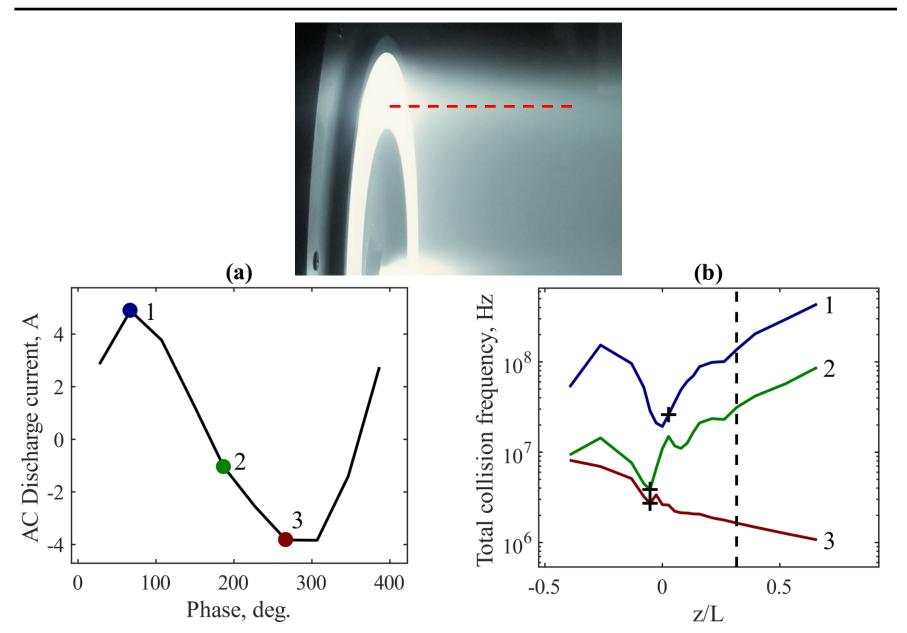
Electron cyclotron drift instability one example







Generating additional data on transport in Hall thrusters





Summary

- Fluid models are attractive tool for modeling Hall effect thrusters
- Need to account for known anomalous electron transport in these models with a type of closure: typically anomalous effects represented with scalar collision frequency (or mobility)
- Data-driven, ML methods can be employed to find functional form for this anomalous collision frequency
- Predictions from ML results yield
 - Improved results compared to first-principles models for anomalous collision frequency
 - ML algorithm also yields physical insight into dominant terms governing transport
- ML is a promising path forward for closing anomalous electron transport problem. Predictive capability has applications ranging from predictive design to qualification through analysis.
- On-going challenges include
 - Extrapolation
 - Data-generation